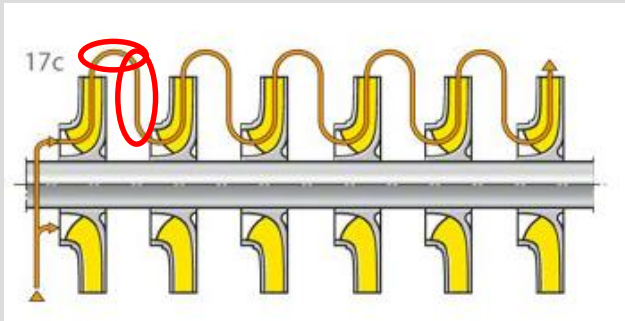
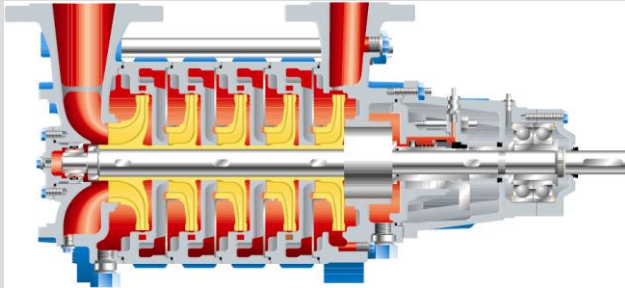
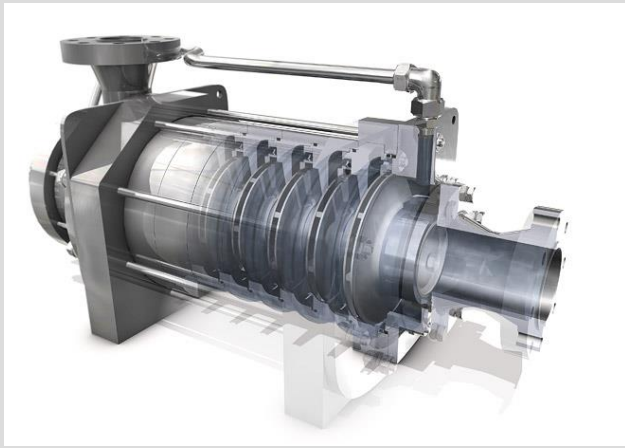




# Application of self-programmed custom features and special meridional contours for the design of multi-stage pumps

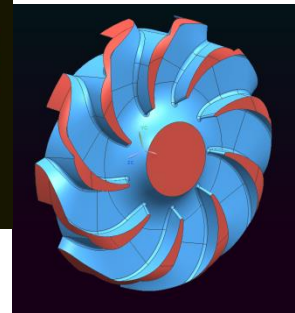
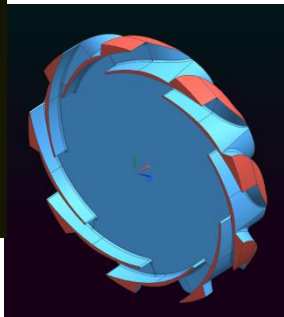
1. *Overview*
2. *Design parameters*
3. *Implementation in CAESES to support design process*
4. *Examples*
5. *Conclusion*

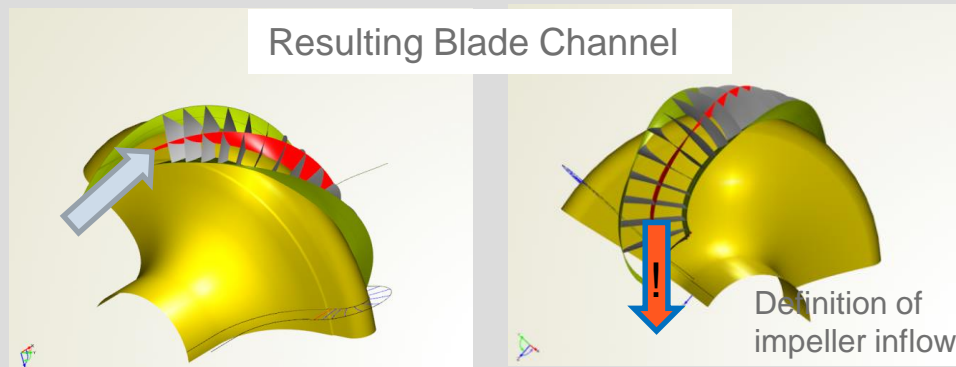
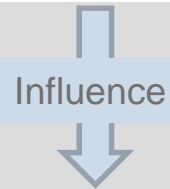
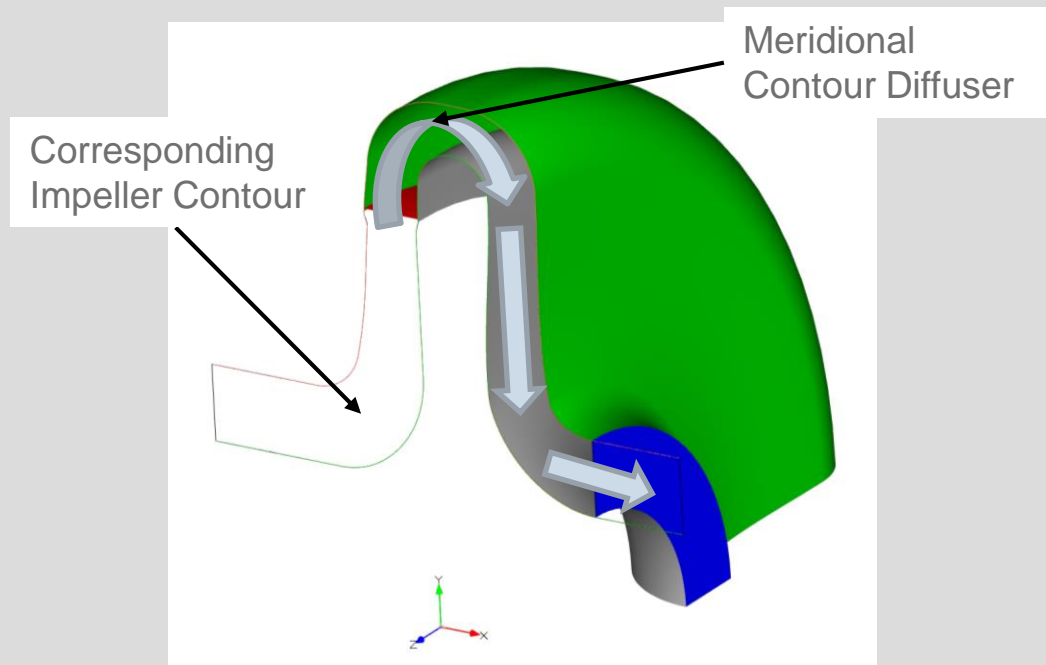


## Overview

# Multi Stage Pumps

- Tandem arrangements of impellers with serial throughflow to economical increase the pump head
- Typically one stage consists of impeller, diffuser vane and back vane
- Serves to collect the impeller outflow, convert the kinetic energy into static pressure and bring it back to the impeller of the next stage
- At requirement of small outer pump diameter diffuser- and back vane can be combined to a continuous flow channel





# Meridional contour design

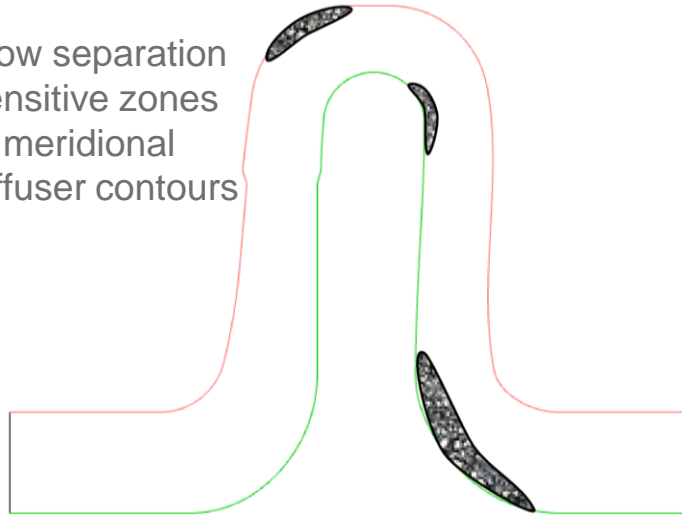
## Overview

- Basis of centrifugal pump design
- Defines main dimensions of the pump and fluid flow characteristics in the blade channel
- Meridional contour is influencing blade channel design
- Optimal values of blade variables for a certain meridional contour maybe different if another contour was given

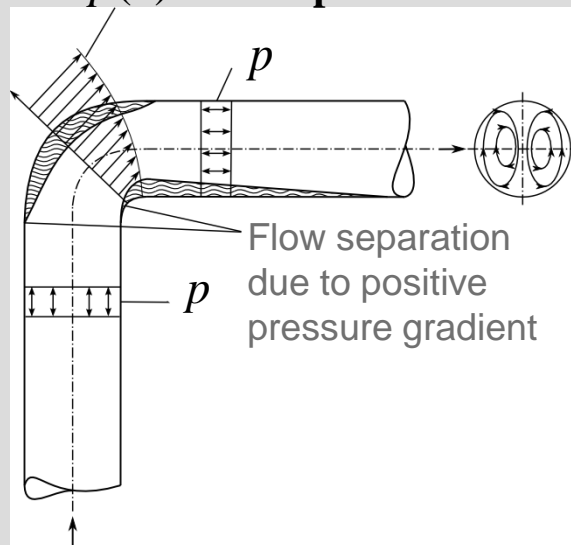
Question: What are suitable design criterias for meridional contours?



Flow separation  
sensitive zones  
in meridional  
diffuser contours



### $p(r)$ Radial pressure distribution



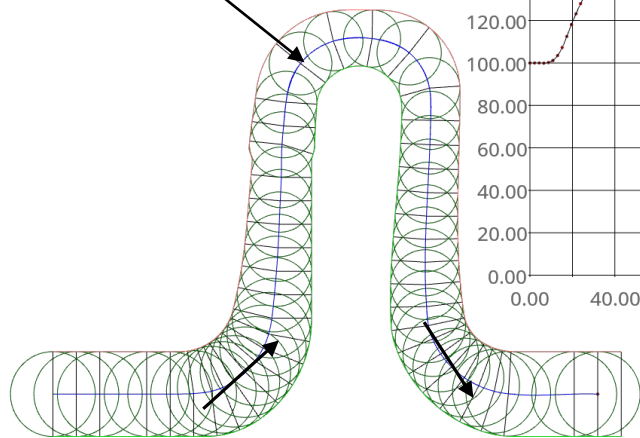
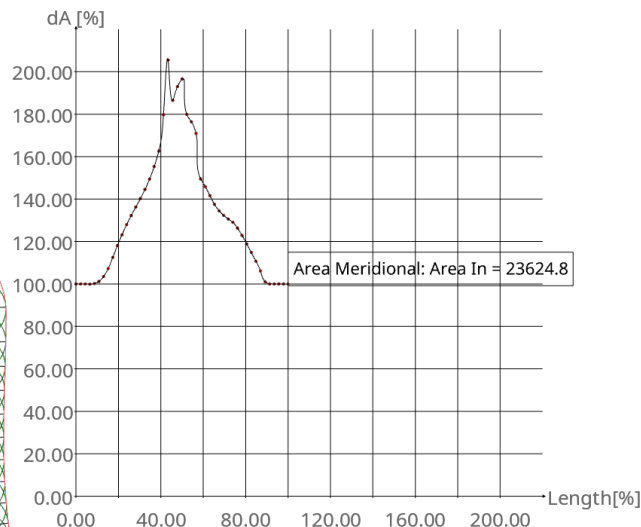
# Design Criteria for Meridional Contours

## Basics

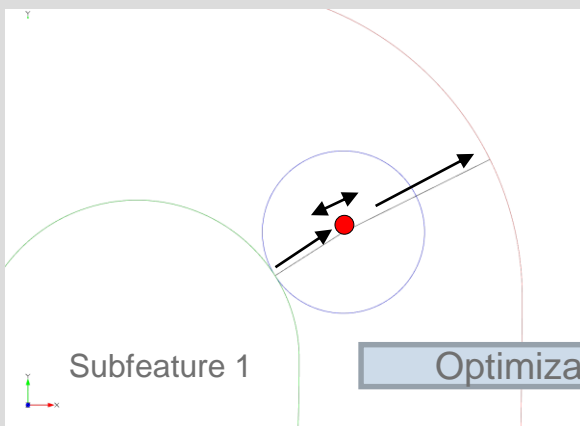
Flow characteristics:

- Comparable to serial elbow flow arrangements
- Due to curved flow path non-uniform flow is generated
- Avoid large pressure gradients by:
  1. Defining hub and shroud by a given smooth meridional cross section distribution between inlet and outlet
  2. Reduce flow channel curvature

Spanwise geometrical position  $s=0.5$

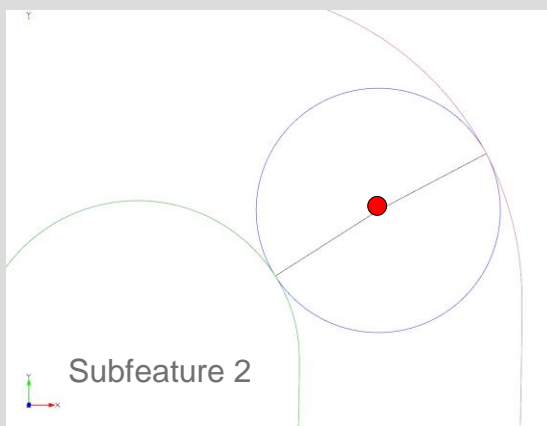


Iteration of Subfeature 1 and Subfeature 2 along contour



Subfeature 1

Optimization



Subfeature 2

## Implementation in CAESSES

### 1. Changing in Cross Section Area

- If flow directly follows the meridional contour shortest distance between hub and shroud at given points along contour is needed

Implementation:

- Define point normal to hub and find parameter of shortest distance to shroud curve
- Optimization of circle center position
- Feature iteration along contour
- Queries to find correct point offset direction:
  - Change of curvature algebraic sign
  - Curves with no curvature
- In case of spanwise curved blades interpolation curve of circle center points gives additional pathline

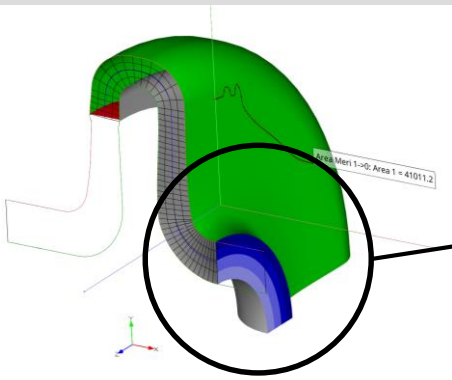
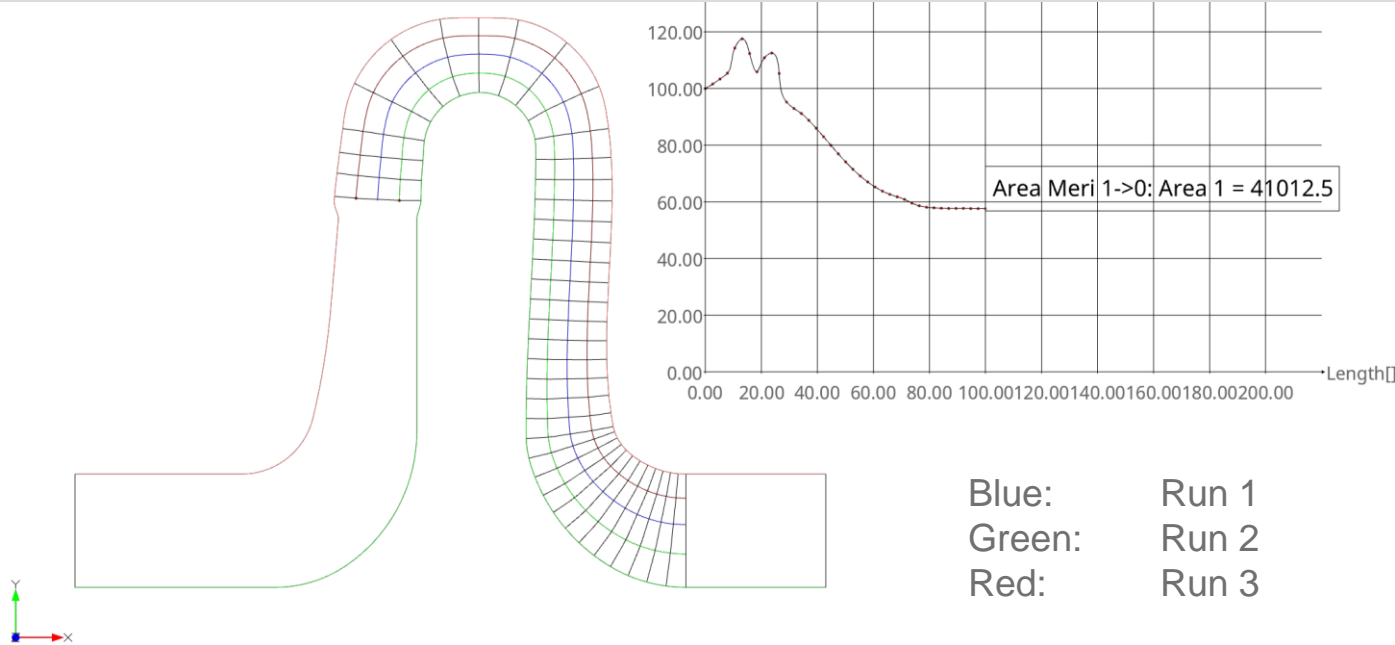
# Implementation in CAESES

## Flow Channels of Constant Mass Flow

- In case of pumps with higher specific speed blade description with more than 3 pathlines is necessary
- Transition from geometrical pathline description to a velocity dependent approach is realized
- Aim is to have const. velocities along each pathlines

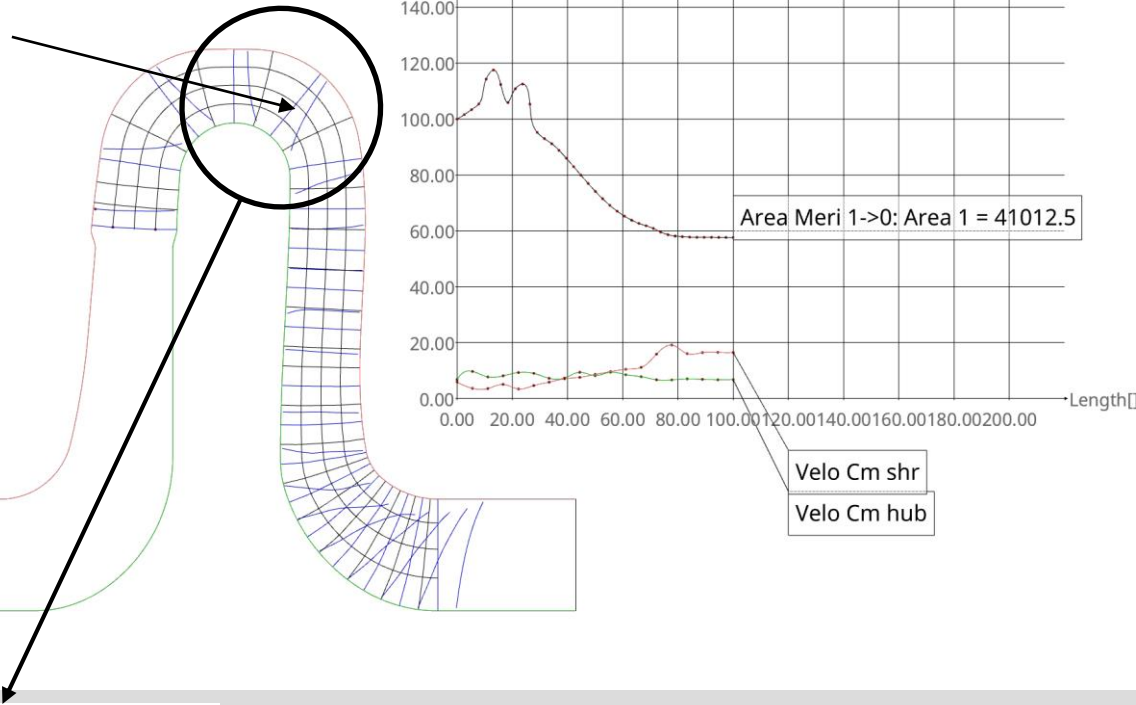
### Implementation:

- Optimization criteria: Constant cross section area of generated flow channels
- Feature to generate pathlines has to be applied 3 times



Difference between inscribe circles and constant area

Orthogonal  
Trajectory



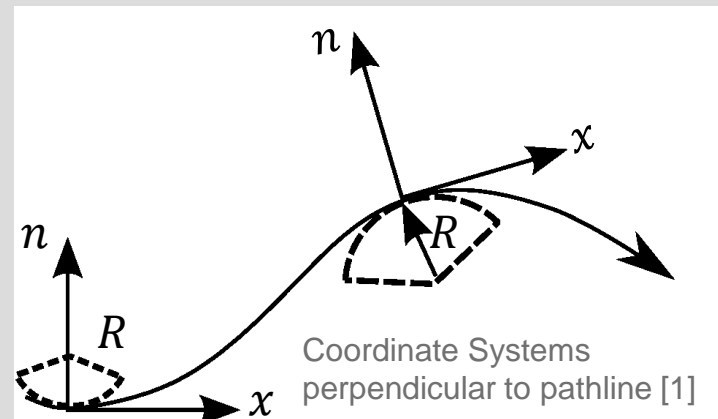
## Implementation in CAESES

### 2. Curvature Dependent Velocity Distribution

- Basis orthogonal grid to pathlines
- Along orthogonal trajectory calculation of the curvature dependent velocity distribution is possible
- Equation derived from Potential Flow Theory [1]
 
$$-\frac{c}{R} - \frac{\partial c}{\partial n} = 0$$
- In a coordinate system normal to the pathlines velocity distribution depends only on local curvature and the velocity gradient
- Solving differential equation by discretizing the pathline curvature along the orthogonal trajectory

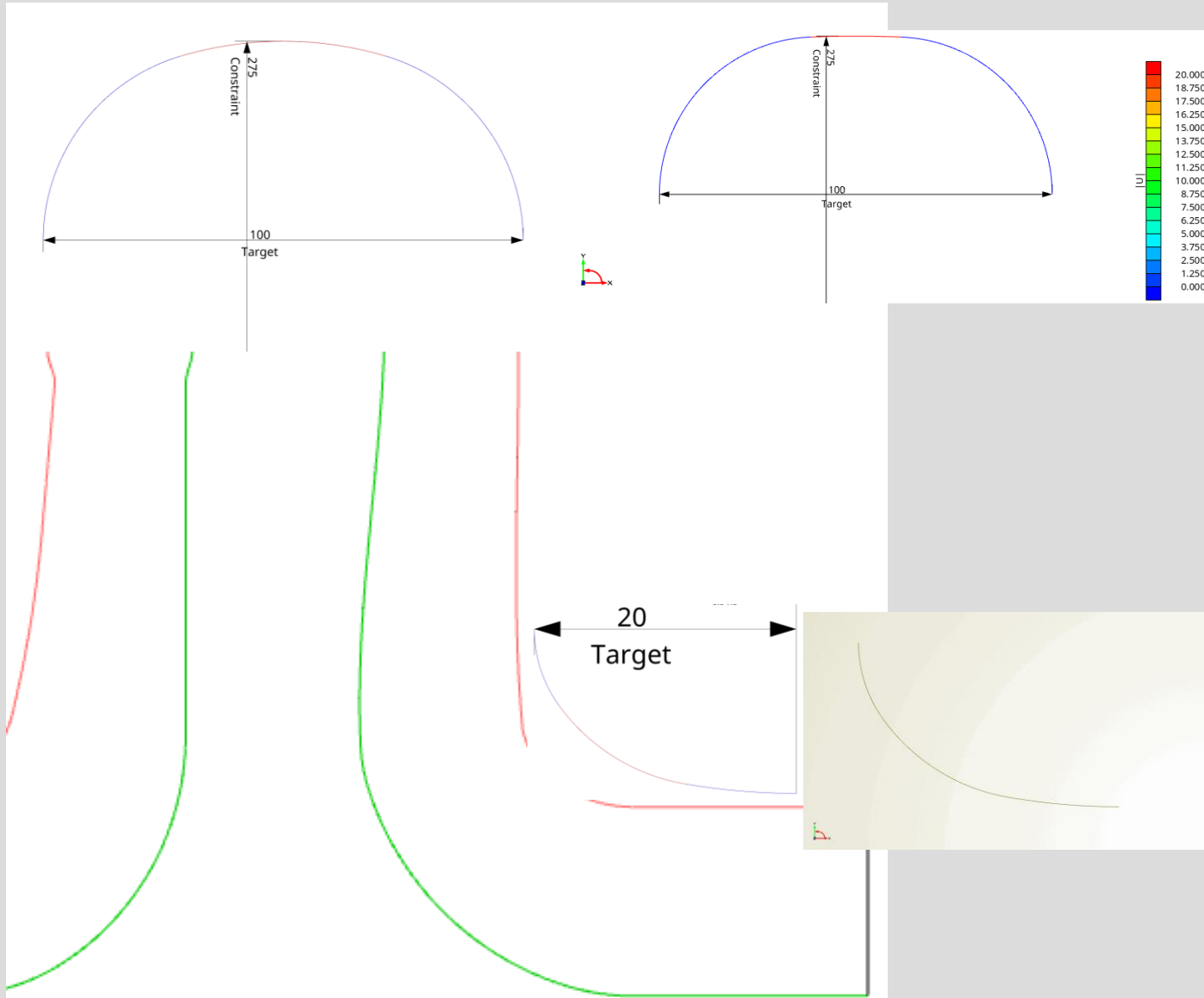
$$c_i = c_0 \cdot e^{curv_i(n) \cdot \Delta n_i} \quad Q = \sum_0^i A_i c_i$$

/1/ W. Albring, Angewandte Strömungslehre



# Meridional Contour Functional Design

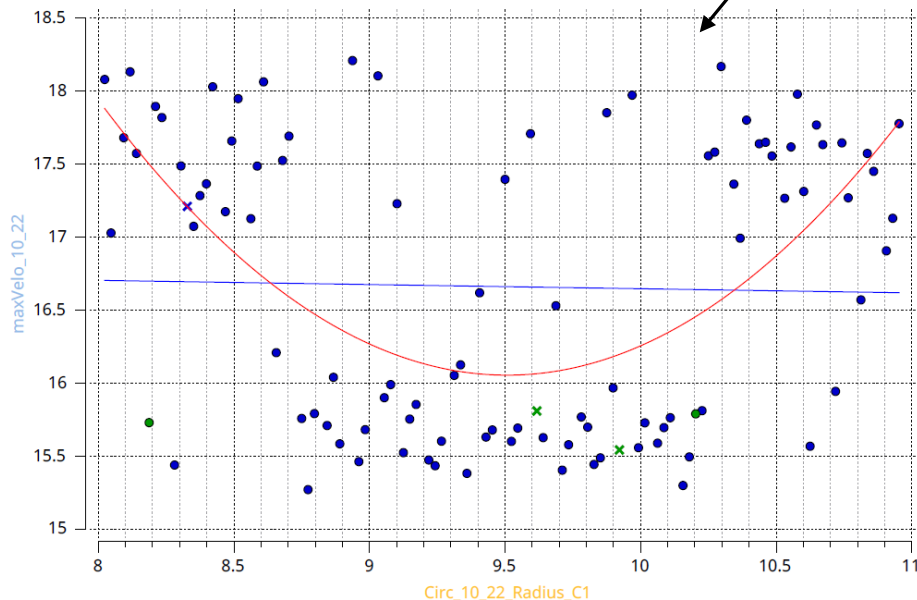
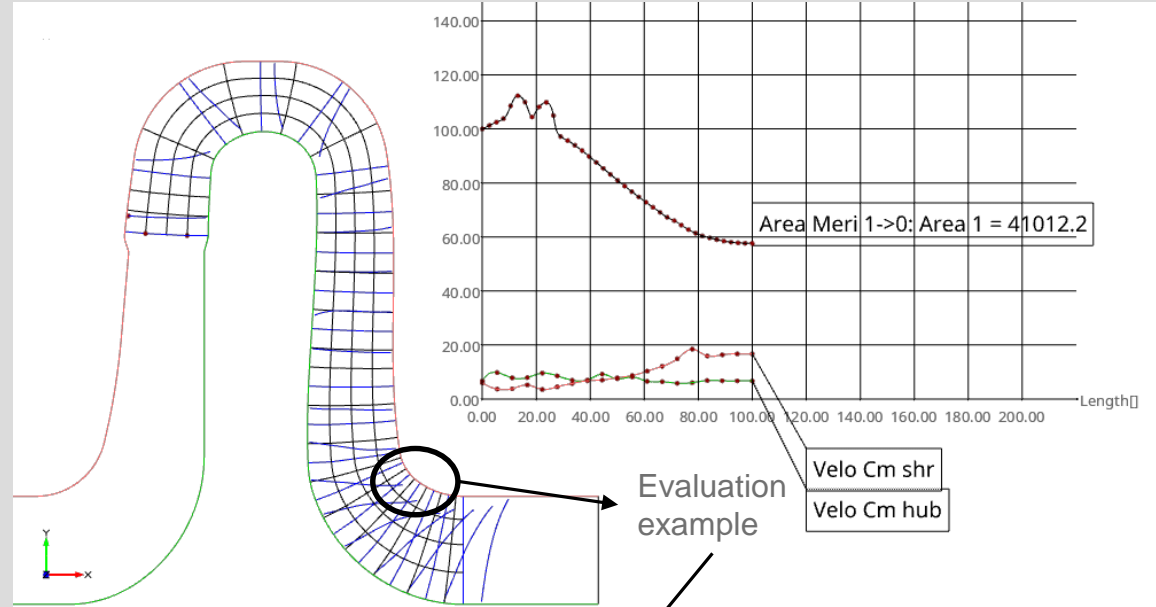
- For cause of reproducibility and documentation reason realization with as less splines as possible
- To have similar degree of freedom combination of three circles to define curvature
- Application of geometry constraints via design engines





# Meridional Contour Design Examples

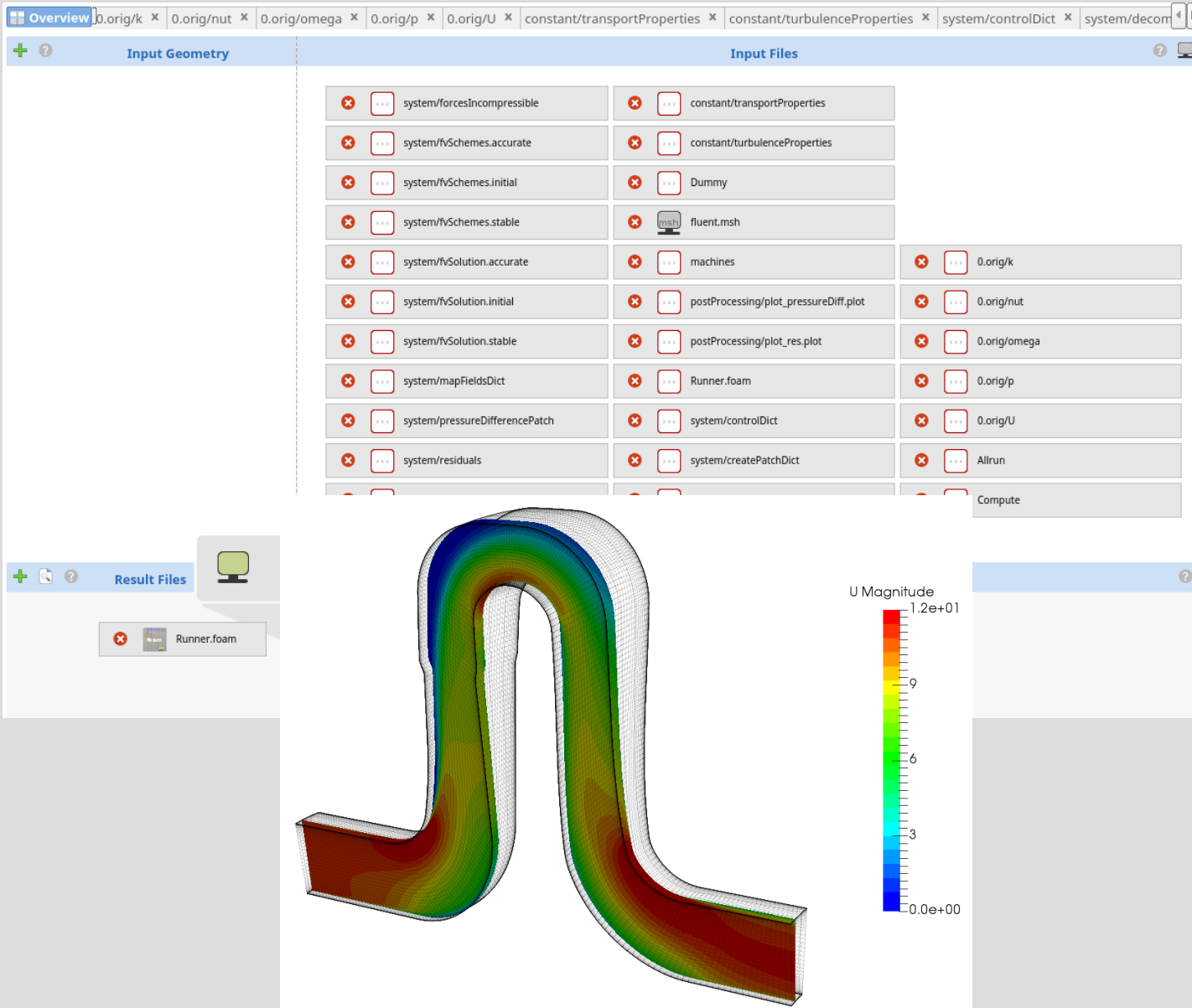
- 19 design variables varied by Sobol Design Engine
- Evaluating criterias are course of meridional cross section area and velocity distribution at hub and shroud
- Not always clear dependencies between design variables and evaluation criteria's

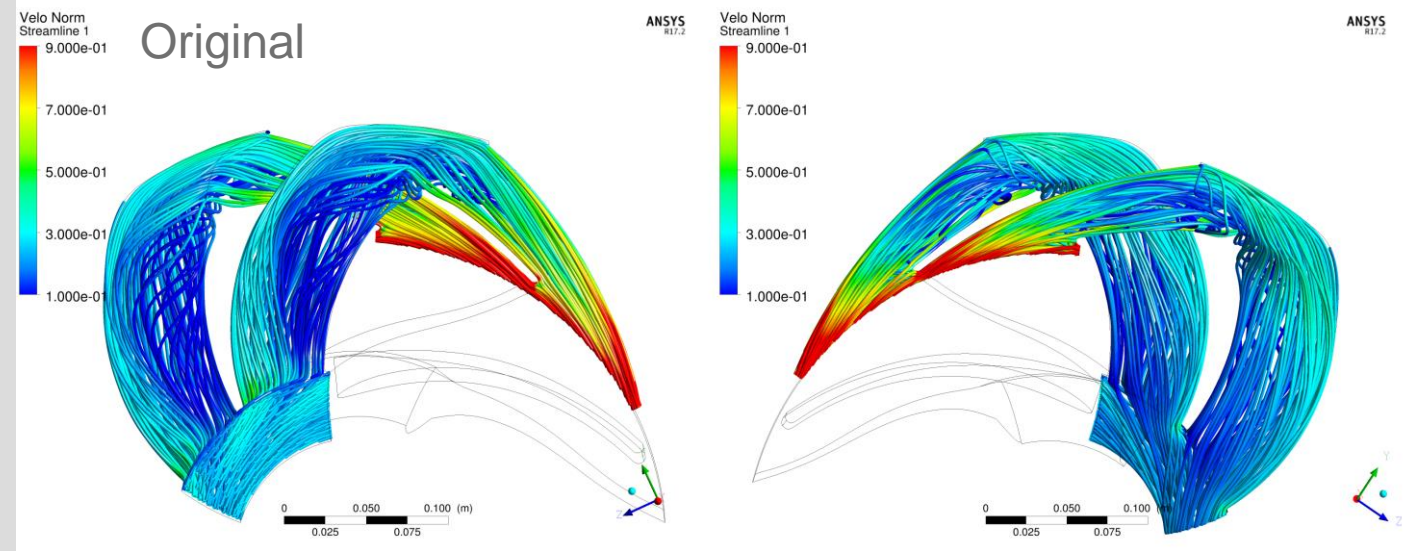


	Design Variable	Lower	Value	Upper	Active	
1	Dist_center_00	19	20	20	<input checked="" type="checkbox"/>	✗
2	Circ_00_22_Position	0	0.005	0.1	<input checked="" type="checkbox"/>	✗
3	Circ_00_22_Radius_C1	35	38	40	<input checked="" type="checkbox"/>	✗
4	Circ_00_22_Radius_C2	55	64	65	<input checked="" type="checkbox"/>	✗
5	Circ_00_22_Radius_C3	50	53	60	<input checked="" type="checkbox"/>	✗
6	Dist_center_10	46	47	48	<input checked="" type="checkbox"/>	✗
7	Circ_10_22_Position	0.1	0.2	0.25	<input checked="" type="checkbox"/>	✗
8	Circ_10_22_Radius_C1	8	10	11	<input checked="" type="checkbox"/>	✗
9	Circ_10_22_Radius_C2	15	17	20	<input checked="" type="checkbox"/>	✗
10	Circ_10_22_Radius_C3	25	31	32	<input checked="" type="checkbox"/>	✗
11	C1_Radius_00	15	19	20	<input checked="" type="checkbox"/>	✗
12	C2_Radius_00	20	20	25	<input checked="" type="checkbox"/>	✗
13	C3_Radius_00	12	15.5	17	<input checked="" type="checkbox"/>	✗
14	C1_Radius_10	35	39	45	<input checked="" type="checkbox"/>	✗
15	C2_Radius_10	0	500	500	<input type="checkbox"/>	✗
16	C3_Radius_10	40	41	43	<input checked="" type="checkbox"/>	✗
17	Opt_Radius_00_22	56	57	59	<input checked="" type="checkbox"/>	✗
18	Opt_Radius_10_22	20	26	27	<input checked="" type="checkbox"/>	✗
19	Span00_OuterRad	248	248.6	250	<input checked="" type="checkbox"/>	✗

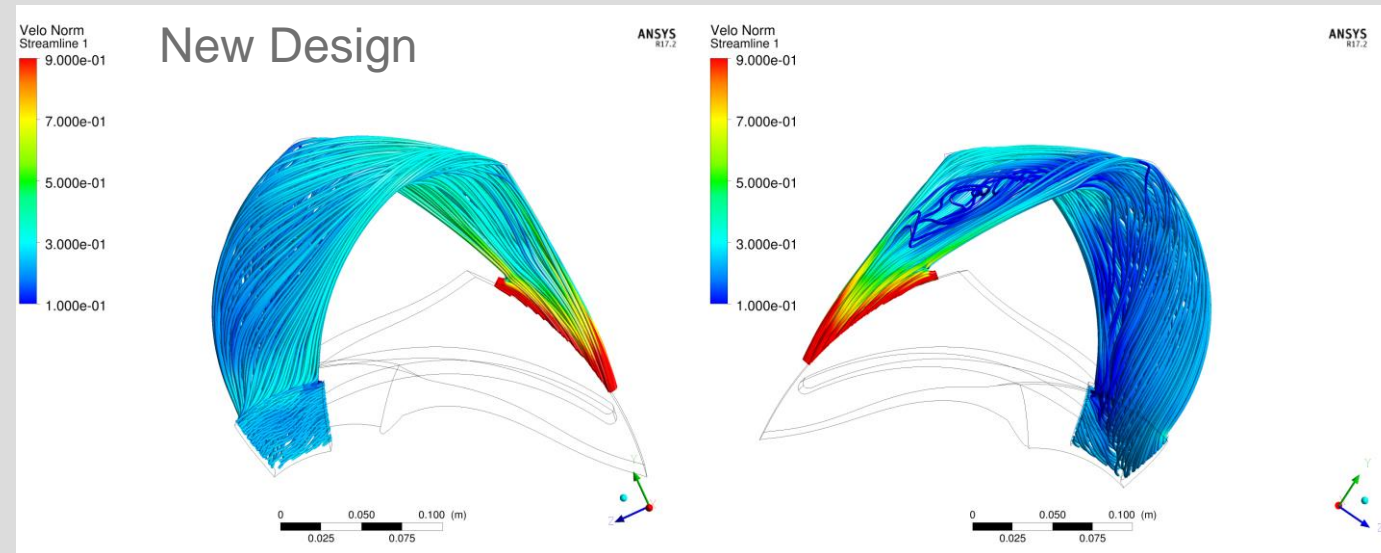
# Meridional Contour Viscous Calculation

- Ongoing design investigation of promising designs with viscous calculation
- Taken flow separation into account
- Coupling CAESES with ICEMCFD and OpenFOAM to get an additional objective function - pressure loss
- Velocity inlet and pressure outlet boundary conditions



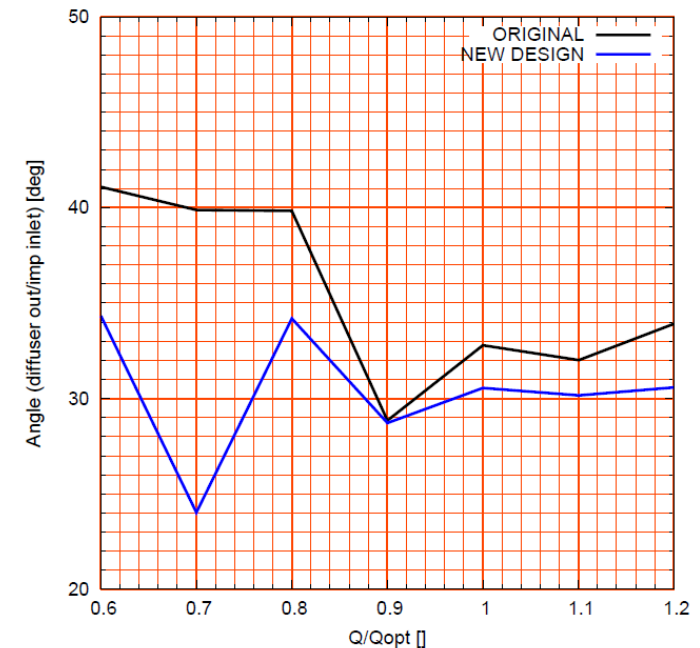


$$Q/Q_{opt} = 0.6$$



# Channel Flow Improvement

- Similar results at best operating point
- Increase of flow stability in part load
- Decreased swirl at diffuser outlet



# Conclusion

- Implementation of tools to design and evaluate meridional contours in CAESES
- Extend these evaluation criteria by coupling CAESES with OpenFOAM for approaching viscous evaluating criteria
- Application in designing diffusers of multistage pumps

